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$$\mu_k = 0.25, \quad \mu_k = 0.2$$

$\vec{q}_B = 1 \text{ m} \uparrow$, system released from rest

$$\vec{v}_B = ?$$

Constraint condition:

$$x_B + x_A + x_A = R$$

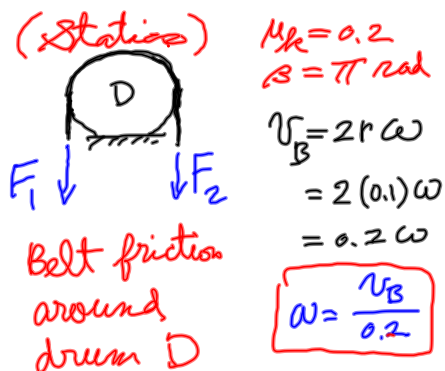
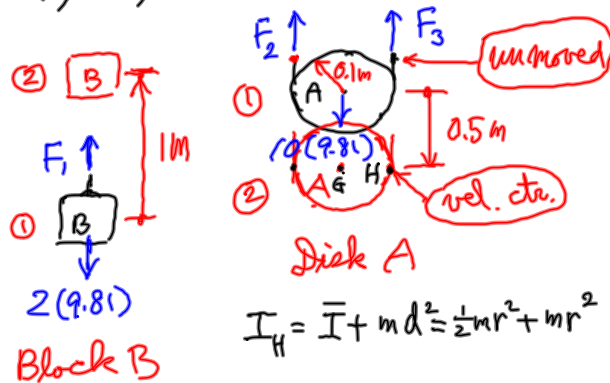
$$2x_A + x_B = R$$

$$2(\Delta x_A) + \Delta x_B = 0$$

$$\Delta x_B = \vec{q}_B = 1 \text{ m} \uparrow \quad \therefore \Delta x_B = -1 \text{ m}$$

$$2(\Delta x_A) + (-1) = 0 \quad \therefore \Delta x_A = 0.5 \text{ m}$$

We may let the tensions in the segments of the cord be F_1 , F_2 , & F_3 , as indicated.



$$T_1 + U_{1 \rightarrow 2} = T_2 \text{ for block B}$$

$$0 + [2(9.81)(-1) + F_1(1)] = \frac{1}{2}(2)v_B^2 \quad \dots \dots \dots (1)$$

$$T_1 + U_{1 \rightarrow 2} = T_2 \text{ for disk A}$$

$$0 + [F_2(-1) + 10(9.81)(0.5)] = \frac{1}{2} \left[\frac{1}{2}(10)(0.1)^2 + 10(0.1)^2 \right] \left(\frac{v_B}{0.2} \right)^2 \quad \dots \dots \dots (2)$$

Belt friction is static for belt friction around drum D

$$F_2 = F_1 e^{0.2\pi} \quad (T_2 = T_1 e^{\mu_k \beta}) \quad \dots \dots \dots (3)$$

$$\therefore F_1 = \square, \quad F_2 = \square, \quad v_B = \square$$

$$\vec{q}_B = \square \uparrow$$