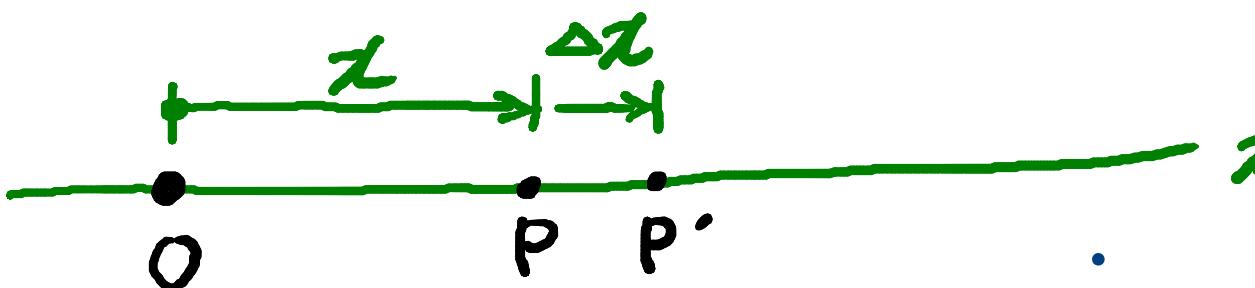


Rectilinear motion of a particle



x : position variable

t : time

a : acceleration $a = \frac{dv}{dt}$

If the acceleration is constant, we can let $a = a_c = \text{const.}$

$$a_c = \frac{dv}{dt} \quad \int_{v_0}^v a_c dt = \int_{v_0}^v dv$$

$$\boxed{v = v_0 + a_c t}$$

Δx : displacement

$$v = \frac{dx}{dt} = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} \quad \text{velocity}$$

$j = \frac{da}{dt}$ jerk

$$a_c t \Big|_0^t = v \Big|_{v_0}^v \quad a_c(t-0) = v - v_0$$

$$\frac{dx}{dt} = v = v_0 + a_c t \quad dx = (v_0 + a_c t) dt$$

$$\int_{x_0}^x dx = \int_0^t (v_0 + a_c t) dt$$

$$x \Big|_{x_0}^x = v_0 t + \frac{1}{2} a_c t^2 \Big|_0^t$$

$$x - x_0 = v_0 t + \frac{1}{2} a_c t^2$$

$$\boxed{x = x_0 + v_0 t + \frac{1}{2} a_c t^2}$$

Kinematics

Kinetics